JOURNAL OF THE CHUNGCHEONG MATHEMATICAL SOCIETY Volume **31**, No. 4, November 2018 http://dx.doi.org/10.14403/jcms.2018.31.1.369

# VOLUMES OF GEODESIC BALLS IN HEISENBERG GROUPS

SUNJIN JEONG\* AND KEUN PARK\*\*

ABSTRACT. Let  $\mathbb{H}^3$  be the 3-dimensional Heisenberg group equipped with a left-invariant metric. In this paper we calculate the volumes of geodesic balls in  $\mathbb{H}^3$ . Let  $B_e(R)$  be the geodesic ball with center e(the identity of  $\mathbb{H}^3$ ) and radius R in  $\mathbb{H}^3$ . Then, the volume of  $B_e(R)$ is given by

$$Vol(B_e(R)) = \frac{\pi}{6} \{ -16R + (R^2 + 6) \sin R + (R^3 + 10R) \cos R + (R^4 + 12R^2) \int_0^R \frac{\sin t}{t} dt \}.$$

#### 1. Introduction

Let  $\mathcal{N}$  be a 2-step nilpotent Lie algebra with an inner product  $\langle , \rangle$ and N its unique simply connected 2-step nilpotent Lie group with the left invariant metric induced by  $\langle , \rangle$  on  $\mathcal{N}$ . Let  $\mathcal{Z}$  be the center of  $\mathcal{N}$ . Then  $\mathcal{N}$  is represented by the direct sum of  $\mathcal{Z}$  and its orthgonal complement  $\mathcal{Z}^{\perp}$ .

For each  $Z \in \mathcal{Z}$ , a skew symmetric linear transformation  $j(Z) : \mathcal{Z}^{\perp} \to \mathcal{Z}^{\perp}$  is defined by  $j(Z)X = (adX)^*Z$  for  $X \in \mathcal{Z}^{\perp}$ . Or, equivalently,

$$\langle j(Z)X, Y \rangle = \langle [X,Y], Z \rangle$$

for all  $X, Y \in \mathcal{Z}^{\perp}$ .

A 2-step nilpotent Lie algebra  ${\mathcal N}$  is said to be an algebra of Heisenberg type if

$$j(Z)^2 = -|Z|^2 id$$

2010 Mathematics Subject Classification: 53C30, 22E25.

Correspondence should be addressed to Keun Park, kpark@ulsan.ac.kr.

Received June 04, 2018; Accepted September 01, 2018.

Key words and phrases: Heisenberg group, geodesic ball.

 $<sup>\</sup>ast\ast$  This work was partially supported by 2012 Research Fund of University of Ulsan.

for all  $Z \in \mathcal{Z}$ . And a Lie group N is said to be a group of Heisenberg type if its Lie algebra  $\mathcal{N}$  is of Heisenberg type.

The Heisenberg groups are examples of Heisenberg type. That is, let  $n \ge 1$  be any integer and  $\{X_1, \dots, X_n, Y_1, \dots, Y_n\}$  a basis of  $\mathbb{R}^{2n} = \mathcal{V}$ . Let  $\mathcal{Z}$  be an one dimensional vector space spanned by  $\{Z\}$ . Define

$$X_i, Y_i] = -[Y_i, X_i] = Z$$

for any  $i = 1, 2, \dots, n$  with all other brackets are zero. Give on  $\mathcal{N} = \mathcal{V} \oplus \mathcal{Z}$  the inner product such that the set of vectors  $\{X_i, Y_i, Z | i = 1, 2, \dots, n\}$  forms an orthonormal basis. Let N be the simply connected 2-step nilpotent group of Heisenberg type which is determined by  $\mathcal{N}$  and equipped with a left-invariant metric induced by the inner product in  $\mathcal{N}$ . The group N is called the (2n + 1)-dimensional Heisenberg group and denoted by  $\mathbb{H}^{2n+1}$ .

In this paper, we calculate the volumes of the geodesic balls on the Heisenberg group  $\mathbb{H}^3$ :

THEOREM 1.1. Let  $B_e(R)$  be the geodesic ball with center e (the identity of  $\mathbb{H}^3$ ) and radius R in  $\mathbb{H}^3$ . Then, the following holds.

$$Vol(B_e(R)) = \frac{\pi}{6} \{ -16R + (R^2 + 6)\sin R + (R^3 + 10R)\cos R + (R^4 + 12R^2) \int_0^R \frac{\sin t}{t} dt \}.$$

For a Riemannian manifold M and  $p \in M$ , the volume growth,  $VG_p(M)$  of M at p is defined by

$$VG_p(M) = \inf\{x \in R | \lim_{r \to \infty} \frac{Vol(B_p(r))}{r^x} = 0\}.$$

If M is a Lie group with a left invariant metric, then we see that  $VG_p(M) = VG_q(M)$  for any  $p, q \in M$ . In this case, it is denoted by VG(M).

COROLLARY 1.2. The volume growth,  $VG(\mathbb{H}^3)$  of  $\mathbb{H}^3$  is given as follows;

$$VG(\mathbb{H}^3) = 4.$$

#### 2. Preliminaries

Let  $\mathcal{N}$  be a 2-step nilpotent Lie algebra with an inner product  $\langle , \rangle$ and N be its unique simply connected 2-step nilpotent Lie group with

the left invariant metric induced by <,> on  $\mathcal{N}$ . The center of  $\mathcal{N}$  is denoted by  $\mathcal{Z}$ . Then  $\mathcal{N}$  can be expressed as the direct sum of  $\mathcal{Z}$  and its orthogonal complement  $\mathcal{Z}^{\perp}$ .

Recall that for  $Z \in \mathcal{Z}$ , a skew symmetric linear transformation j(Z):  $\mathcal{Z}^{\perp} \to \mathcal{Z}^{\perp}$  is defined by  $j(Z)X = (\mathrm{ad}X)^*Z$  for  $X \in \mathcal{Z}^{\perp}$ . Or, equivalently,

$$\langle j(Z)X, Y \rangle = \langle [X, Y], Z \rangle$$

for  $X, Y \in \mathbb{Z}^{\perp}$ . A 2-step nilpotent Lie group N is said to be of Heisenberg type if

$$j(Z)^2 = -|Z|^2 \operatorname{id}$$

for all  $Z \in \mathcal{Z}$ .

Let  $\gamma(t)$  be a curve in N such that  $\gamma(0) = e$  (identity element in N) and  $\gamma'(0) = X_0 + Z_0$  where  $X_0 \in \mathbb{Z}^{\perp}$  and  $Z_0 \in \mathbb{Z}$ . Since  $\exp: \mathbb{N} \to \mathbb{N}$ is a diffeomorphism ([9]), the curve  $\gamma(t)$  can be expressed uniquely by  $\gamma(t) = \exp(X(t) + Z(t))$  with

$$\begin{aligned} X(t) &\in \mathcal{Z}^{\perp} \,, \qquad X'(0) = X_0 \,, \quad X(0) = 0 \\ Z(t) &\in \mathcal{Z} \,, \qquad Z'(0) = Z_0 \,, \quad Z(0) = 0 \,. \end{aligned}$$

A. Kaplan ([7, 8]) shows that the curve  $\gamma(t)$  is a geodesic in N if and only if

$$X''(t) = j(Z_0)X'(t), Z'(t) + \frac{1}{2}[X'(t), X(t)] \equiv Z_0.$$

The following Lemma is useful in the later.

LEMMA 2.1. [2] Let N be a simply connected 2-step nilpotent Lie group with a left invariant metric, and let  $\gamma(t)$  be a geodesic of N with  $\gamma(0) = e$  and  $\gamma'(0) = X_0 + Z_0$  where  $X_0 \in \mathbb{Z}^{\perp}$  and  $Z_0 \in \mathbb{Z}$ . Then, one has

$$\gamma'(t) = dl_{\gamma(t)}(X'(t) + Z_0), t \in \mathbb{R}$$

where  $X'(t) = e^{tj(Z_0)}X_0$  and  $l_{\gamma(t)}$  is the left translation by  $\gamma(t)$ .

Throughout this paper, different tangent spaces will be identified with  $\mathcal{N}$  via left translation. So, in above lemma, we can consider  $\gamma'(t)$  as

$$\gamma'(t) = X'(t) + Z_0 = e^{tj(Z_0)}X_0 + Z_0.$$

Let  $\mathbb{H}^3$  be the 3 dimensional Heisenberg group with a left invariant metric and  $\mathcal{H}$  its Lie algebra. Let  $\gamma(t)$  be an unit speed geodesic on  $\mathbb{H}^3$ with  $\gamma(0) = e$ (the identity element of  $\mathbb{H}^3$ ) and  $\gamma'(0) = X_0 + Z_0$  where  $X_0 \in \mathbb{Z}^{\perp}$  and  $Z_0 \in \mathbb{Z}$ . Assume that  $X_0 \neq 0$  and  $Z_0 \neq 0$ . Then

$$\left\{X_0 + Z_0, \frac{|Z_0|}{|X_0|}X_0 - \frac{|X_0|}{|Z_0|}Z_0, \frac{1}{|Z_0||X_0|}j(Z_0)X_0\right\}$$

is an orthonormal basis of  $\mathcal{H}$ . Let

$$e_1(t) = \frac{|Z_0|}{|X_0|} X'(t) - \frac{|X_0|}{|Z_0|} Z_0,$$
  
$$e_2(t) = \frac{1}{|Z_0||X_0|} j(Z_0) X'(t).$$

Then,  $\{\gamma'(t), e_1(t), e_2(t)\}$  is an orthonormal frame along  $\gamma(t)$  on  $\mathbb{H}^3$ .

We start the following Proposition.

PROPOSITION 2.2. [5] For each k = 1, 2, let  $J_k(t)$  be the Jacobi field with  $J_k(0) = 0, J'_k(0) = e_k(0)$ . Then, we have that

$$\begin{bmatrix} J_1(t) \\ J_2(t) \end{bmatrix} = B(t) \begin{bmatrix} e_1(t) \\ e_2(t) \end{bmatrix}$$

where

$$B(t) = \frac{1}{|Z_0|^3} \begin{bmatrix} \sin(|Z_0|t) - (1 - |Z_0|^2)|Z_0|t & |Z_0|(\cos(|Z_0|t) - 1) \\ |Z_0|(1 - \cos(|Z_0|t)) & |Z_0|^2\sin(|Z_0|t) \end{bmatrix}.$$

COROLLARY 2.3. [1, 6] Let  $\mathbb{H}^3$  be the (2n+1)-dimensional Heisenberg group and  $\mathcal{N}$  its Lie algebra. Let  $\gamma(t)$  be an unit speed geodesic in Nwith  $\gamma(0) = e$ (the identity element of N) and  $\gamma'(0) = X_0 + Z_0$  where  $X_0 \in \mathcal{Z}^{\perp}$  and  $Z_0 \in \mathcal{Z}$ . If  $Z_0 \neq 0$ , then all the conjugate points along  $\gamma$ are at  $t \in \frac{2\pi}{|Z_0|}\mathbb{Z}^* \cup \mathbb{A}$  where

$$\mathbb{Z}^* = \{\pm 1, \pm 2, \ldots\}$$

and

$$\mathbb{A} = \left\{ t \in \mathbb{R} - \{0\} | (1 - |Z_0|^2) \frac{|Z_0|t}{2} = \tan \frac{|Z_0|t}{2} \right\}.$$

In particular,  $\frac{2\pi}{|Z_0|}$  is the first conjugate point of e along  $\gamma$ . If  $Z_0 = 0$ , then there are no conjugate points along  $\gamma$ .

For the conjugate points of another type of Heisenberg groups, Quaternionic Heisenberg groups  $\mathbb{H}^{4n+3}$ , see [4].

G. Walschap [10] showed that the first conjugate loci and the cut loci are equal in the case of the groups of Heisenberg type or the 2step nilpotent groups with one-dimensional center. So, we consider the geodesic balls  $B_e(r)$  with the radius  $r \leq 2\pi$ .

In [5], C. Jang, J. Park and K. Park obtained a fomula of the volumes of geodesic balls in the Heisenberg group  $\mathbb{H}^3$  as the form of power series.

THEOREM 2.4. [5] Let  $B_e(R)$  be the geodesic ball with center e and radius R in  $\mathbb{H}^3$ . Then, the following holds.

$$Vol(B_e(R)) = 4\pi \left(\frac{R^3}{3} + 2\sum_{n=2}^{\infty} (-1)^n \frac{R^{2n+1}}{(2n+1)!(2n-1)(2n-3)}\right).$$

## 3. Main results

LEMMA 3.1. [5]  

$$\det(B(t)) = \frac{1}{|Z_0|^4} \{ 2(1 - \cos(|Z_0|t)) - (1 - |Z_0|^2) |Z_0| t \sin(|Z_0|t) \}$$

$$\geq 0.$$

LEMMA 3.2. Let n be a natural number and  $f : [0, x] \to R$  have continuous n-th derivatives. Assume that for  $k = 0, 1, \dots, n-1$ , the  $\lim_{t\to 0^+} \frac{f^{(k)}(t)}{t^{n-k}}$  exists and  $\frac{f^{(n)}(t)}{t}$  is integrable on [0, x]. Then,  $\frac{f(t)}{t^{n+1}}$  is integrable on [0, x] and the following holds.

$$\int_0^x \frac{f(t)}{t^{n+1}} dt = -\sum_{k=0}^{n-1} \frac{1}{n(n-1)\cdots(n-k)} \left[ \frac{f^{(k)}(t)}{t^{n-k}} \right]_{0^+}^{x^-} + \frac{1}{n!} \int_0^x \frac{f^{(n)}(t)}{t} dt$$

where

$$\left[\frac{f^{(k)}(t)}{t^{n-k}}\right]_{0^+}^x = \lim_{t \to x^-} \frac{f^{(k)}(t)}{t^{n-k}} - \lim_{t \to 0^+} \frac{f^{(k)}(t)}{t^{n-k}}.$$

*Proof.* We use the mathematical induction. For n = 1, we see that

$$\int_0^x \frac{f(t)}{t^2} dx = \int_0^x f(t) d(-\frac{1}{t}) = -\left[\frac{f(t)}{t}\right]_{0^+}^{x^-} + \int_0^x \frac{f^{(1)}(t)}{t} dt.$$

Suppose that

$$\int_0^x \frac{f(t)}{t^{n+1}} dt = -\sum_{k=0}^{n-1} \frac{1}{n(n-1)\cdots(n-k)} \left[ \frac{f^{(k)}(t)}{t^{n-k}} \right]_{0^+}^{x^-} + \frac{1}{n!} \int_0^x \frac{f^{(n)}(t)}{t} dt$$

holds. Then,

$$\int_0^x \frac{f(t)}{t^{n+2}} dt = \int_0^x f(t) d\left(-\frac{1}{n+1}t^{-(n+1)}\right)$$
$$= -\frac{1}{n+1} \left[\frac{f(t)}{t^{n+1}}\right]_{0^+}^{x^-} + \frac{1}{n+1} \int_0^x \frac{f^{(1)}(t)}{t^{n+1}} dt.$$

Since

$$\int_0^x \frac{f^{(1)}(t)}{t^{n+1}} dx$$
  
=  $-\sum_{k=0}^{n-1} \frac{1}{n(n-1)\cdots(n-k)} \left[ \frac{f^{(k+1)}(t)}{t^{n-k}} \right]_{0^+}^{x^-} + \frac{1}{n!} \int_0^x \frac{f^{(n+1)}(t)}{t} dt,$ 

we have that

$$\int_0^x \frac{f(t)}{t^{n+2}} dt = -\sum_{k=0}^n \frac{1}{(n+1)(n+1-1)\cdots(n+1-k)} \left[\frac{f^{(k)}(t)}{t^{n+1-k}}\right]_{0^+}^{x^-} + \frac{1}{(n+1)!} \int_0^x \frac{f^{(n+1)}(t)}{t} dt.$$

This completes the proof.

LEMMA 3.3. For R > 0, the followings are hold.

$$(1) \int_0^R \frac{2t + t\cos t - 3\sin t}{t^5} dt$$
  
=  $\frac{R^{-4}}{24} \left( -16R + (R^2 + 18)\sin R + (R^3 - 2R)\cos R + R^4 \int_0^R \frac{\sin t}{t} dt \right).$ 

$$(2)\int_0^R \frac{\sin t - t\cos t}{t^3} dt = \frac{R^{-2}}{2} \left( -\sin R + R\cos R + R^2 \int_0^R \frac{\sin t}{t} dt \right).$$

*Proof.* (1) Let  $f(t) = 2t + t \cos t - 3 \sin t$ . Then, direct calculations give that

$$\left[\frac{f(t)}{t^4}\right]_{0^+}^R = R^{-4}(2R + R\cos R - 3\sin R),$$
$$\left[\frac{f^{(1)}(t)}{t^3}\right]_{0^+}^R = R^{-3}(2 - 2\cos R - R\sin R),$$
$$\left[\frac{f^{(2)}(t)}{t^2}\right]_{0^+}^R = R^{-2}(\sin R - R\cos R),$$
$$\left[\frac{f^{(3)}(t)}{t}\right]_{0^+}^R = \sin R.$$

Since  $f^{(4)}(t) = \sin t + t \cos t$ , by Lemma 3.2, we have that  $\int_{0}^{R} \frac{f(t)}{t^{5}} dt$   $= -\sum_{k=0}^{3} \frac{1}{4 \times 3 \times \dots \times (4-k)} \left[ \frac{f^{(k)}(t)}{t^{4-k}} \right]_{0^{+}}^{R^{-}} + \frac{1}{4!} \int_{0}^{R} \frac{f^{(4)}(t)}{t} dt$   $= \frac{R^{-4}}{24} \left( -16R + (R^{2} + 18) \sin R + (R^{3} - 2R) \cos R + R^{4} \int_{0}^{R} \frac{\sin t}{t} dt \right).$ Proof of (2) is similar to (1).

We introduce the volume formula of geodesic balls in Riemannian manifolds, which is well-known. For example, see [3]. Let M be a Riemannian manifold with a metric g and  $p \in M$ . Take an orthonormal basis  $\{u_1, u_2, \dots, u_n\}$  of  $T_pM$  and let  $(x_1, x_2, \dots, x_n)$  be the coordinates determined by  $\{u_1, u_2, \dots, u_n\}$ . This local coordinate system is called the normal coordinate system at p. It is easy to show that  $\frac{\partial}{\partial x_{im}} = (d \exp_p) \sum_{i=1}^n x_i u_i(u_i)$  where  $m = \exp_p(\sum_{i=1}^n x_i u_i)$ . Then, the volume form  $v_g$  on  $U_p$  is given by

$$v_g = \sqrt{\det\left(g(\frac{\partial}{\partial x_i}, \frac{\partial}{\partial x_j})\right)} dx_1 \wedge dx_2 \wedge \dots \wedge dx_n$$

where  $g_{ij}$  is the metric coefficients of g in  $U_p$ . Therefore, the volume of the geodesic ball  $B_p(r)$  is given by

$$Vol(B_p(r)) = \int_{\exp_p^{-1}(B_p(r))} \exp_p^* v_g.$$

Let  $\gamma(t)$  be the unit speed geodesic in M with  $\gamma(0) = p$ ,  $\gamma'(0) = u_1$ and let  $J_i(t)$  be the Jacobi field with  $J_i(0) = 0$  and  $J'_i(0) = u_i$  for each  $i = 2, 3, \dots, n$ . Then we know that

$$(d\exp_p)_{tu_1}u_1 = \gamma'(t)$$

and

$$(d\exp_p)_{tu_1}u_i = \frac{1}{t}J_i(t)$$

for each  $i = 2, 3, \dots, n$ . So, we see that

$$\sqrt{\det\left(g(\frac{\partial}{\partial x_i}, \frac{\partial}{\partial x_j})\right)} = t^{-(n-1)}\sqrt{\det(g(J_i(t), J_j(t)))}.$$

Sunjin Jeong and Keun Park

Hence, we have that

$$\exp_p^* v_g = t^{-(n-1)} \sqrt{\det(g(J_i(t), J_j(t)))} dx_1 dx_2 \cdots dx_n$$
$$= \sqrt{\det(g(J_i(t), J_j(t)))} dt du$$

where du denote the canonical measure of the unit sphere  $S^{n-1}$ . Therefore, by Fubini's Theorem we get that

$$Vol(B_p(r)) = \int_{S^{n-1}} \int_0^r \sqrt{\det(g(J_i(t), J_j(t)))} dt du.$$

THEOREM 3.4. Let  $0 \leq R \leq 2\pi$  and  $B_e(R)$  be the geodesic ball with center e and radius R in  $\mathbb{H}^3$ . Then, the following holds.

$$Vol(B_e(R)) = \frac{\pi}{6} \{ -16R + (R^2 + 6)\sin R + (R^3 + 10R)\cos R + (R^4 + 12R^2) \int_0^R \frac{\sin t}{t} dt \}.$$

*Proof.* Using Proposition 2.2, we have that

$$det (< J_i(t), J_j(t) >) = det (J_i(t) \cdot J_j(t)) = det \left( \begin{bmatrix} J_1(t) \\ J_2(t) \end{bmatrix} \begin{bmatrix} J_1(t) & J_2(t) \end{bmatrix} \right) = det \left( B(t) \begin{bmatrix} e_1(t) \\ e_2(t) \end{bmatrix} \cdot t \left( B(t) \begin{bmatrix} e_1(t) \\ e_2(t) \end{bmatrix} \right) \right) = det (B(t) \cdot t (B(t))) = \left( \frac{1}{|Z_0|^4} \{ 2(1 - \cos(|Z_0|t)) - (1 - |Z_0|^2) |Z_0|t \sin(|Z_0|t) \} \right)^2.$$

Since

$$\det(B(t)) = \frac{1}{|Z_0|^4} \{ 2(1 - \cos(|Z_0|t)) - (1 - |Z_0|^2) |Z_0| t \sin(|Z_0|t) \} \ge 0,$$

we see that

$$\sqrt{\det\left(\langle J_i(t), J_j(t) \rangle\right)} = \frac{1}{|Z_0|^4} \{ 2(1 - \cos(|Z_0|t)) - (1 - |Z_0|^2) |Z_0| t \sin(|Z_0|t) \}.$$

Let  $u = (x_1, x_2, x_3) \in S^2$  and

$$f(x_3,t) = \frac{1}{x_3^4} \{ 2(1 - \cos(x_3 t)) - (1 - x_3^2)x_3 t \sin(x_3 t) \}.$$

Then, we see that

$$Vol(B_e(R)) = \int_{S^2} \int_0^R f(x_3, t) dt du.$$

Since area element du on the sphere  $S^2$  is given by

$$du = \frac{1}{\sqrt{1 - (x_1^2 + x_2^2)}} dx_1 dx_2,$$

we have that

$$Vol(B_e(R)) = 2 \int_D \int_0^R f(\sqrt{1 - (x_1^2 + x_2^2)}, t) \frac{1}{\sqrt{1 - (x_1^2 + x_2^2)}} dt dx_1 dx_2,$$

where

$$D = \{(x_1, x_2) | x_1^2 + x_2^2 \le 1\}.$$

Changing the coordinates on D to polar coordinates, we have

$$Vol(B_e(R)) = 4\pi \int_0^1 \int_0^R f(\sqrt{1-r^2}, t) \frac{r}{\sqrt{1-r^2}} dt dr.$$

Replacing  $x = \sqrt{1 - r^2}$ , we see that

$$Vol(B_e(R)) = 4\pi \int_0^1 \int_0^R f(x,t) dt dx$$

where

$$f(x,t) = \frac{1}{x^4} \{ 2(1 - \cos(xt)) - (1 - x^2)x_3t\sin(xt) \}.$$

Since

$$\int_0^R f(x,t)dt = \frac{2Rx + Rx\cos(Rx) - 3\sin(Rx)}{x^5} + \frac{\sin(Rx) - Rx\cos(Rx)}{x^3},$$

we have that 
$$V_{ol}(B(B))$$

$$= 4\pi \int_0^1 \int_0^R f(x,t) dt dx$$
  
=  $4\pi \int_0^1 \left( \frac{2Rx + Rx\cos(Rx) - 3\sin(Rx)}{x^5} + \frac{\sin(Rx) - Rx\cos(Rx)}{x^3} \right) dx$   
=  $4\pi \left( R^4 \int_0^R \frac{2t + t\cos t - 3\sin t}{t^5} dt + R^2 \int_0^R \frac{\sin t - t\cos t}{t^3} dt \right).$ 

By Lemma 3.3, we see that

$$Vol(B_e(R)) = 4\pi \left( R^4 \int_0^R \frac{2t + t\cos t - 3\sin t}{t^5} dt + R^2 \int_0^R \frac{\sin t - t\cos t}{t^3} dt \right)$$
$$= \frac{\pi}{6} \left\{ -16R + (R^2 + 6)\sin R + (R^3 + 10R)\cos R + (R^4 + 12R^2) \int_0^R \frac{\sin t}{t} dt \right\}.$$

This completes the proof.

### References

- J. Berndt, F. Tricerri, and L. Vanhecke, Geometry of generalized Heisenberg groups and their Damak-Ricci harmonic extensions, Comptes rendus de l academie des sciences serie i-mathematique, **318** (1994), no. 5, 471-476.
- [2] P. Eberlein, Geometry of 2-step nilpotent Lie groups with a left invariant metric, Ann. Scient. Ecole Normale Sup. 27 (1994), no. 5, 611-660.
- [3] S. Gallot, D. Hulin, and J. Lafontaine, *Riemannian geometry*, Springer-Verlag, Berlin, 1990.
- [4] C. Jang, J. Kim, Y. Kim, and K. Park, Conjugate points on the quaternionic Heisenberg group, Jour. of Korean Math. Soc. 40 (2003), 61-72.
- [5] C. Jang, J. Park, and K. Park, Geodesic spheres and balls of the Heisenberg groups, Commun. Korean Math. Soc. 25 (2010), 83-96.
- [6] C. Jang and K. Park, Conjugate points on 2-step nilpotent groups, Geom. Dedicata, 79 (2000), 65-80.
- [7] A. Kaplan, Riemannian nilmanifolds attached to clifford modules, Geom. Dedicata, 11 (1981), 127-136.
- [8] A. Kaplan, On the geometry of groups of Heisenberg type, Bull. London Math. Soc. 15 (1983), 35-42.
- [9] M. S. Raghunathan, Discrete subgroups of Lie groups, Springer-Verlag, 1972.
- [10] G. Walschap, Cut and conjugate loci in two-step nilpotent Lie groups, Jour. of Geometric Analysis, 7 (1997), 343-355.

w

378

\*

Department of Mathematics University of Ulsan Ulsan 44610, Republic of Korea *E-mail*: sjudong@hanmail.net

\*\*

Department of Mathematics University of Ulsan Ulsan 44610, Republic of Korea *E-mail*: kpark@ulsan.ac.kr